

# CS 7800: Advanced Algorithms

## Class 6: Dynamic Programming III

- Knapsack
- Shortest Paths

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# The Knapsack Problem

- **Input:**  $n$  items for your knapsack with value  $v_i$  and weight  $w_i$  and a capacity  $T \in \mathbb{N}$
- **Output:** the most valuable subset of items that fits in the knapsack
  - **subset**  $S \subseteq \{1, \dots, n\}$
  - **value**  $V_S = \sum_{i \in S} v_i$  as large as possible
  - **weight**  $W_S = \sum_{i \in S} w_i$  at most  $T$

# Writing the Recurrence

# Solving the Recurrence

# Knapsack Problem Recap

- Can solve the knapsack problem in time  $O(nT)$ 
  - First example of **dynamic programming with multiple variables in the recurrence**
  - First example of a **pseudopolynomial-time algorithm**—compare to naïve  $O(2^n)$  time algorithm
  - Later on we may see an **approximation algorithm** that solves knapsack in time  $O(n)$  with small error

# Shortest Paths

- **Input:** Directed, weighted graph  $G = (V, E, \{w_e\})$ , source node  $s$ 
  - Possibly negative edge lengths  $w_e \in \mathbb{R}$
  - No negative-length cycles!
- **Output:** Two arrays  $d, p$ 
  - $d[u]$  is the length of the shortest  $s \rightsquigarrow u$  path
  - $p[u]$  is the final hop on shortest  $s \rightsquigarrow u$  path

# Structure of Shortest Paths

- If  $(u, v) \in E$ , then  $d(s, v) \leq d(s, u) + w(u, v)$  for every node  $s \in V$
- If  $(u, v) \in E$ , and  $d(s, v) = d(s, u) + w(u, v)$  then there is a shortest  $s \rightsquigarrow v$ -path ending with  $(u, v)$

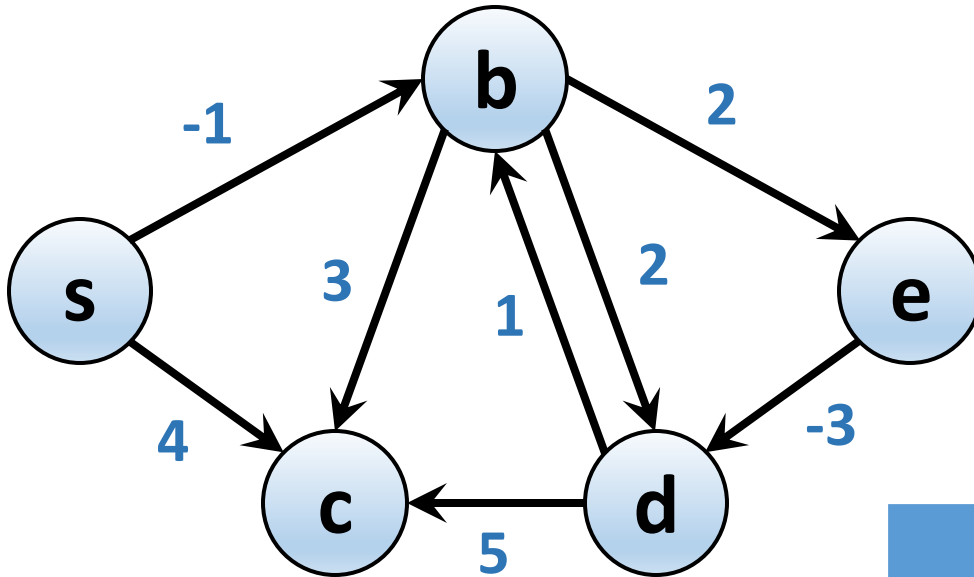
# Writing the Recurrence



# Solving the Recurrence

# Writing the Recurrence: Attempt 2

## Solving the Recurrence: Attempt 2



	0	1	2	3	4
s	0				
b	$\infty$				
c	$\infty$				
d	$\infty$				
e	$\infty$				

# Shortest Paths Summary

- **Input:** Directed, weighted graph  $G = (V, E, \{w_e\})$ , and a source node  $s$
- **Output:** Two arrays  $d, p$ 
  - $d[u]$  is the length of the shortest  $s \rightsquigarrow u$  path
  - $p[u]$  is the final hop on some shortest  $s \rightsquigarrow u$  path
- **Negative lengths:** Bellman-Ford solves the single-source shortest paths problem in  $O(nm)$  worst-case time, or finds a negative cycle
  - Often much faster in practice with suitable appropriate optimizations